

17660

16117

3 Hours / 100 Marks

Seat No.

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- Instructions* –
- (1) All Questions are *Compulsory*.
 - (2) Answer each next main Question on a new page.
 - (3) Illustrate your answers with neat sketches wherever necessary.
 - (4) Figures to the right indicate full marks.
 - (5) Assume suitable data, if necessary.
 - (6) Mobile Phone, Pager and any other Electronic Communication devices are not permissible in Examination Hall.

Marks

- 1. Attempt any FIVE of the following:** **20**
- a) Draw a block diagram of ‘Mechatronics System’ and indicate the basic elements on it.
 - b) List velocity sensors and with diagram explain any one type.
 - c) State four advantages of CNC system. What are G codes and M codes?
 - d) State the characteristics of ‘Quick opening control valve’.
 - e) State the function of manipulator and end effector.
 - f) Define the term ‘MEMS’. List down the various engineering applications of MEMS.
 - g) Enlist the various mechanical actuating system and explain any one in brief.

P.T.O.

- 2. Attempt any FOUR of the following:** **16**
- a) What is 'Mechatronics'? State its importance in engineering with suitable examples.
 - b) State the function of 'Signal Conditioner' in measurement system.
 - c) Explain how a PLC can be used to handle an analog input.
 - d) State the working principle of 'Solenoid valve' with neat sketch.
 - e) Explain the basic elements of Robotic system with block diagram.
 - f) Describe the working of PLC based automatic car park barrier system with block diagram.
- 3. Attempt any FOUR of the following:** **16**
- a) Explain the function of PLC. Draw a block diagram of basic PLC configuration.
 - b) State and explain working principle of 'Hall effect sensor' with sketch.
 - c) Draw block diagram of 'Fuzzy logic' controller and explain function of each block.
 - d) Explain the principle of process control valves.
 - e) Draw and explain the basic elements of 'MEMS'.
 - f) Explain with sketch, principle of working of 'Pick and place Robot'.
- 4. Attempt any TWO of the following:** **16**
- a) Explain with sketch, torque measurement using:
 - (i) Stroboscope method
 - (ii) Capacitive method
 - b) Explain with diagram how micro-controller is used for stepper motor control.
 - c) Describe with sketch, basic details of;
 - (i) Poppet valve
 - (ii) Shuttle valve

- 5. Attempt any FOUR of the following:** **16**
- a) State and explain working principle of Tacho generators.
 - b) Give the significance of Transducer and sensor with suitable example.
 - c) State the characteristics of PD and PID controllers with their control action equations.
 - d) Draw a block diagram indicating the application of Fuzzy logic control in fully automatic washing machine.
 - e) Explain the concept of degree of freedom of Robot with sketch.
 - f) Enlist and explain the various components of Mechatronic system.
- 6. Attempt any TWO of the following:** **16**
- a) Describe the principle of operation of;
 - (i) Linear actuators
 - (ii) DC motors
 - b) Explain the constructional features of MEMS accelerometer used in airbag sensors for car safety.
 - c) Explain with block diagram, working of micro-controller based anti lock braking system.
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